

THE NON-DEFINABILITY OF THE SPACES OF TSIRELSON AND SCHLUMPRECHT

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ABSTRACT. We prove the impossibility of finding explicit finitary definitions of the spaces of Tsirelson and Schlumprecht in real-valued logic.

INTRODUCTION

For decades now, it has been an open question whether Tsirelson’s space [Tsi74, FJ74] admits a finitary explicit definition. In this paper we use ideas of model theory to prove the non-existence of a finitary definition of Tsirelson’s space. Here, “finitary” means “first-order”. We use Keisler’s framework of model theory for general (real-valued) structures [Kei23], which provides the most general approach for the logical analysis of structures endowed with real-valued functions.

Our argument has two main ingredients: a model-theoretic one and an analytic one. The analytic ingredient is a non-uniform convergence argument that relies on a construction involving fast-growing functions. The model-theoretic ingredient of the proof relies on Shelah’s theory of stability [She90]. The aforementioned non-uniform convergence result allows us to deduce that the Tsirelson does not have a finitary definition (in the sense of Gaifman-Shelah [Gai76, She71]) in the complete theory of structure $(c_{00}, \|\cdot\|_n)_{n \in \mathbb{N}}$, where $\|\cdot\|_n$ is the n -th approximant of the Tsirelson norm. For the precise statement, see Theorem 14.

Our approach extends to other implicitly defined normed spaces, although the key analytic ingredient must be proved on a case-by-case basis. To illustrate this, in the last section of the paper, we extend our non-definability result to Schlumprecht’s space [Sch91].

The only technical prerequisite of the paper is familiarity with model theory for real-valued structures. We use the recent framework of Keisler’s general structures [Kei23]; however, our arguments can be easily translated to the well-known formalism of metric structures *à la* Ben Yaacov-Usvyatsov [BYU10] (see remarks 10).

The paper is organized as follows: In section 1, we recall the definition of the Tsirelson space of Figiel and Johnson and prove that the convergence of the Tsirelson approximates towards the Tsirelson norm is non-uniform. In section 2, we introduce the model-theoretic point of view and exhibit the link between definability and uniform convergence. Recalling the non-uniformity lemmas of section 1, we deduce the non-definability of the Tsirelson norm. This is the main result of the paper. In section 3, we refine the approach of section 2 to deduce the non-definability of Schlumprecht’s space.

Gower and Odell, independently, posed the question whether every Banach space that has an explicitly defined norm contains ℓ_p or c_0 ; see [Gow95], [Ode02, Question 3, page 201]. In a separate publication [DI], we offer a positive answer to this question.

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This paper is dedicated to the memory of Boris Tsirelson. We were honored when he wrote to us expressing his pleasure for the result presented here.

1. THE TSIRELSON SPACE

1.1. The Tsirelson space of Figiel and Johnson. Let us start this section by recalling the construction of the Tsirelson space of Figiel-Johnson [FJ74]. (The reader is referred to [CS89] for a comprehensive treatment of Tsirelson-like spaces.)

If E, F are finite non-empty subsets of $\mathbb{N} = \{1, 2, 3, \dots\}$, we write $E \leq F$ if $\max E \leq \min F$, and $E < F$ if $\max E < \min F$. We will also write $n \leq E$ for $\{n\} \leq E$.

Let c_{00} denote the space of all finite real scalar sequences, and let $\{e_j\}_{j=1}^{\infty}$ be the canonical basis of c_{00} . For any $x = \sum_{n=1}^{\infty} a_n e_n$ in c_{00} and any $1 \leq E \subset \mathbb{N}$, define

$$Ex = \sum_{n \in E} a_n e_n.$$

A collection of $m \geq 1$ nonempty sets E_1, E_2, \dots, E_m of natural numbers is *admissible* if $m \leq E_1 < E_2 < \dots < E_m$. Define a sequence of norms $\{\|\cdot\|_k\}_{k=0}^{\infty}$ on c_{00} inductively as follows. For fixed $x \in c_{00}$, say $x = \sum_{n=1}^{\infty} a_n e_n$, let

$$\|x\|_0 = \max_n |a_n|$$

and, for $k \geq 0$,

$$\|x\|_{k+1} = \max \left(\|x\|_k, \max \left\{ \frac{1}{2} \sum_{i=1}^m \|E_i x\|_k : 1 \leq m \leq E_1 < E_2 < \dots < E_m \right\} \right),$$

where the innermost maximum is taken over the set of all admissible collections of any size $m \geq 1$. For $x = \sum_{n=1}^{\infty} a_n e_n$, we have

$$\|x\|_k \leq \|x\|_{k+1} \leq \sum_{n=1}^{\infty} |a_n| = \|x\|_{\ell_1};$$

thus, each norm $\|\cdot\|_k$ is 1-Lipschitz with respect to $\|\cdot\|_{\ell_1}$.

1. Definition. The *Tsirelson norm* $\|\cdot\|_T$ on c_{00} is defined as

$$\|x\|_T = \lim_{k \rightarrow \infty} \|x\|_k. \quad (x \in c_{00})$$

Tsirelson's space, denoted \mathcal{T} , is the norm-completion of $(c_{00}, \|\cdot\|_T)$. (As customary, the extension of the Tsirelson norm to Tsirelson's space is still denoted $\|\cdot\|_T$.) The norm $\|\cdot\|_k$ will be called the k -th *iterate* in the construction of the Tsirelson norm.

1.2. Non-uniform convergence of the Tsirelson approximants. As in section 1.1 above, $\|\cdot\|_k$ will denote the k -th iterate in the construction of the Tsirelson norm on c_{00} .

As a preliminary step, we need to construct certain functions of rapid growth. Recall that $g^{(m)}$ denotes the m -fold iteration $g \circ \dots \circ g$ of a function g on a set X , with the usual convention that $g^{(0)}$ is the identity map on X .)

2. Definition. Let functions $f_1, f_2, \dots, f_k, \dots$ on natural numbers be as follows. For all $m \in \mathbb{N}$, let $f_1(m) = m^2$, and recursively define $f_{k+1}(m) = f_k^{(m)}(m)$ for $k \in \mathbb{N}$.

Thus, $f_2(m) = m^{2^{m-1}}$, but f_k for $k > 2$ admits no explicit algebraic expression.

Bellenot had found essentially the same rapid-growth functions in connection, not with the convergence of approximants norms, but with James' non-constructive proof that the standard basis (e_n) of Tsirelson's space is not subsymmetric [Jam64, Bel84].¹

The support $\{n \in \mathbb{N} : a_n \neq 0\}$ of an element $x = \sum_{n \in \mathbb{N}} a_n e_n \in c_{00}$ will be denoted $\text{supp}(x)$. For $c < d \in \mathbb{N}$, we write $[c, d)$ for $\{c, c + 1, \dots, d - 1\}$.

3. Theorem. *For $k \geq 1$, let $\|\cdot\|_k$ be the k -th iterate in the definition of the Tsirelson norm. For every $n \geq 2$ there are vectors $\{x_i\}_{i=1}^n$ in c_{00} such that:*

- (1) x_j is supported on a subset of $\left[f_k^{(j-1)}(n), 2\sqrt{f_k^{(j)}(n)} \right)$, and the sum $x = \sum_{j=1}^n x_j$ is supported on a subset of $\left[n, 2\sqrt{f_{k+1}(n)} \right)$,
- (2) $\|x_i\|_k = \frac{1}{2}$ for $i = 1, 2, \dots, n$,
- (3) $\|x\|_k \leq 1$,
- (4) $\|x\|_{k+1} \geq \frac{n}{4}$, and
- (5) $\|x\|_{\ell_1} \leq 2^{k-1}n$.

We will prove Theorem 3 by induction on k .

Proof of Theorem 3 for $k = 1$ (Base step). Fix $n \geq 2$. For $i = 1, 2, \dots, n$, let $m_i = f_1^{(i-1)}(n) = n^{2^{i-1}}$, and

$$E_i = [m_i, 2m_i) = \{m_i, m_i + 1, \dots, 2m_i - 1\}.$$

Define vectors $\{x_i\}_{i=1}^n$ by

$$x_i = \frac{1}{m_i} \sum_{j=m_i}^{2m_i-1} e_j.$$

Clearly, $\text{supp}(x_i) = E_i = [m_i, 2m_i) = [m_i, 2\sqrt{f_1(m)})$ (since $f_1(m) = m^2 \geq 2m$ for $m \geq 2$).

Thus, x is supported on a subset of $[m_1, 2\sqrt{f_1(m_n)}) = [n, 2\sqrt{f_1^{(n)}(n)}) = [n, 2\sqrt{f_2(n)})$, proving assertion (1). We also have $\|x\|_{\ell_1} = \sum_{i=1}^n \|x_i\|_{\ell_1} = \sum_{i=1}^n \sum_{j=m_i}^{2m_i-1} \frac{1}{m_i} = nm_i/m_i = n$, proving (5). For $i = 1, 2, \dots, n$, we have $\|x_i\|_0 = 1/m_i$, hence (2) follows from

$$\|x_i\|_1 = \frac{1}{2} \sum_{j=m_i}^{2m_i-1} \frac{1}{m_i} = \frac{m_i}{2m_i} = \frac{1}{2}.$$

By disjointness of the supports of the x_i , we have

$$\|x\|_2 \geq \frac{1}{2} \sum_{i=1}^n \|x_i\|_1 = \frac{1}{2} \sum_{i=1}^n \frac{1}{2} = \frac{n}{4},$$

proving (4). It remains to prove (3). Since the norms $\|x_i\|_0 = 1/m_i$ decrease with i , it follows that $\|x\|_0 = \|x_1\|_0 = 1/m_1 = 1/n$. In order to find an upper bound for $\|x\|_1$, we fix q and any admissible

¹More specifically, Bellenot's theorem shows that (e_{n_k}) is not equivalent to the standard basis (e_n) of Tsirelson's space if and only if (n_k) asymptotically grows faster than $(f_k(k))$ with f_k as in definition 2 below. This answers a question of Casazza as to whether "reasonable" sequences (n_k) yield (e_{n_k}) equivalent to (e_n) .

collection $q \leq F_1 < F_2 < \dots < F_q$ in order to find an upper bound for

$$\Sigma := \frac{1}{2} \sum_{j=1}^q \|F_j x\|_0.$$

We may assume that all the sets F_j are nonempty, and

$$\bigcup_{j=1}^q F_j \subset \bigcup_{j=1}^n E_j,$$

since, otherwise, F_j is unnecessarily capturing zero coefficients of x . Without loss of generality we may assume that $q \in F_1$. (Otherwise, Σ is possibly enlarged when one appends to F_1 the integers between q and $\min F_1$.) Henceforth, we fix $1 \leq p \leq n$ such that $m_p \leq q < m_p^2$. There exists a unique index $1 \leq \ell \leq q$ satisfying²

- $\bigcup_{j=1}^{\ell-1} F_j \subset E_p$,
- $F_\ell \cap E_p \neq \emptyset$, and
- $\bigcup_{j=\ell+1}^q F_j \subset \bigcup_{j=p+1}^n E_j$.

By the first and second properties above, $F_1, F_2, \dots, F_{\ell-1}$ and $F_\ell \cap E_i$ are ℓ nonempty disjoint subsets of E_p , so $m_p = \#E_p \geq \ell$. The three properties above imply corresponding inequalities:

- $\|F_j x\|_0 = \frac{1}{m_p}$, for $j = 1, 2, \dots, \ell$, and
- $\|F_j x\|_0 \leq \frac{1}{m_{p+1}}$, for $j = \ell + 1, \dots, q$.

For convenience, let $m_{n+1} = +\infty$. We have

$$\begin{aligned} \Sigma &= \frac{1}{2} \left[\sum_{j=1}^{\ell-1} \|F_j x\|_0 + \|F_\ell x\|_0 + \sum_{j=\ell+1}^q \|F_j x\|_0 \right] \\ &\leq \frac{1}{2} \left[\frac{\ell-1}{m_p} + \frac{1}{m_p} + \sum_{j=\ell+1}^q \frac{1}{m_{p+1}} \right] \\ &= \frac{1}{2} \left[\frac{\ell}{m_p} + \frac{q-\ell}{m_{p+1}} \right] \\ &\leq \frac{1}{2} \left[\frac{\ell}{m_p} + \frac{m_p^2}{m_{p+1}} \right] \quad (\text{since } \ell > 0 \text{ and } q < m_p^2) \\ &\quad (\text{the term } m_p^2/m_{p+1} \text{ above is zero when } \ell = q) \\ &\leq \frac{1}{2} [1 + 1] \quad (\text{since } \ell \leq m_p \text{ and } m_{p+1} \geq m_p^2) \\ &= 1. \end{aligned}$$

This proves (3), finishing the proof of Theorem 3 for $k = 1$. □

Proof of Theorem 3 (Inductive step). Assume the statement in the Theorem holds for some fixed $k \geq 1$. Fix $n \geq 2$. For $1 \leq i \leq n$, let $m_i = f_{k+1}^{(i-1)}(n)$, and for $1 \leq j \leq m_i$, let $m_{ij} = f_k^{(j-1)}(m_i)$. Apply the inductive assumption with m_i in place of n to obtain m_i vectors, say $\{x_{ij}\}_{j=1}^{m_i}$, such that:

²We adopt the standard conventions $\bigcup_{j=b}^{b-1} Z_j = \emptyset$ and $\sum_{j=b}^{b-1} z_j = 0$.

- (1) $\text{supp}(x_{ij}) \subset [m_{ij}, 2\sqrt{f_k(m_{ij})})$ for $1 \leq j \leq m_i$, and the sum $x_i = \sum_{j=1}^{m_i} x_{ij}$ is supported on a subset of $[m_i, 2\sqrt{f_{k+1}(m_i)})$;
- (2) $\|x_{ij}\|_k = \frac{1}{2}$ for $1 \leq j \leq m_i$;
- (3) $\|x_i\|_k \leq 1$,
- (4) $\|x_i\|_{k+1} \geq \frac{m_i}{4}$, and
- (5) $\|x_i\|_{\ell_1} \leq 2^{k-1}m_i$.

For each i , let

$$y_i = \frac{x_i}{2\|x_i\|_{k+1}}.$$

As shown above, the elements y_i ($1 \leq i \leq n$) together with their sum $y = \sum_{i=1}^n y_i$ satisfy (1) of Theorem 3 with $k+1$ in place of k (y is supported on a subset of $[n, 2\sqrt{f_{k+1}(m_n)})$, and $f_{k+1}(m_n) = f_{k+1}^{(n)}(n) = f_{k+2}(n)$). Next, we have

$$\begin{aligned} \|y_i\|_{k+1} &= \frac{1}{2}, \\ \|y_i\|_k &= \frac{\|x_i\|_k}{2\|x_i\|_{k+1}} \leq \frac{1}{2m_i/4} = \frac{2}{m_i}, \\ \|y\|_{k+2} &\geq \frac{1}{2} \sum_{i=1}^n \|y_i\|_{k+1} = \frac{1}{2} \sum_{i=1}^n \frac{1}{2} = \frac{n}{4}, \end{aligned}$$

proving properties (2) and (4) for $k+1$. Property (5) follows from

$$\|y\|_{\ell_1} = \sum_{i=1}^n \|y_i\|_{\ell_1} = \frac{1}{2} \sum_{i=1}^n \frac{\|x_i\|_{\ell_1}}{\|x_i\|_{k+1}} \leq \frac{1}{2} \sum_{i=1}^n \frac{2^{k-1}m_i}{m_i/4} = 2^k n.$$

It remains to show that property (3) holds, i.e., that $\|y\|_{k+1} \leq 1$. Fix q and any admissible collection $q \leq F_1 < F_2 < \dots < F_q$. As in the proof of the case $k=1$, we may assume that $q = \min F_1$, and that for some p we have $m_p \leq q < 2\sqrt{f_{k+1}(m_p)}$. For each i, j , let E_{ij} be the support of y_{ij} , and let $E_i = \bigcup_{j=1}^{m_i} E_{ij}$ be the support of y_i . There exists a unique ℓ ($1 \leq \ell \leq n$) such that (i) $\bigcup_{i=1}^{\ell-1} F_i \subset E_p$, (ii) $F_\ell \cap E_p \neq \emptyset$, and (iii) if $\ell < n$, then $F_{\ell+1} \cap E_p = \emptyset$. For $1 \leq i \leq n$ and $1 \leq j \leq q$, let $z_{ij} = F_j y_i = (E_i \cap F_j)y$. We have $z_{ij} = 0$ if $i < p$ (by (i) above), and $z_{pj} = 0$ if $j > \ell$ (by (iii)). We seek an upper bound for

$$\Sigma := \frac{1}{2} \sum_{j=1}^q \|F_j y\|_k = \frac{1}{2} \sum_{j=1}^q \left\| \sum_{i=p}^n z_{ij} \right\|_k.$$

By the triangle inequality (and omitting zero terms):

$$\begin{aligned} \Sigma &\leq \frac{1}{2} \sum_{i=p}^n \sum_{j=1}^q \|z_{ij}\|_k = \frac{1}{2} \sum_{j=1}^{\ell} \|z_{pj}\|_k + \frac{1}{2} \sum_{i=p+1}^n \sum_{j=\ell}^q \|z_{ij}\|_k \\ &= \Sigma' + \Sigma''. \end{aligned}$$

On the one hand,

$$\Sigma' := \frac{1}{2} \sum_{j=1}^{\ell} \|z_{pj}\|_k \leq \|y_p\|_{k+1} = \frac{1}{2}.$$

On the other hand, assuming $p < n$ (otherwise the quantity Σ'' is zero), since $z_{ij} = F_j y_i$ by definition and $v \mapsto F_j v$ is norm-decreasing, we have

$$\Sigma'' := \frac{1}{2} \sum_{i=p+1}^n \sum_{j=\ell}^q \|z_{ij}\|_k \leq \frac{1}{2} \sum_{i=p+1}^n \sum_{j=\ell}^q \|y_i\|_k.$$

Under the temporary assumption $n \geq 3$, since $k \geq 1$, we have

$$f_{k+1}(n) \geq f_2(n) = f_1^{(n)}(n) \geq f_1^{(3)}(n) = n^8.$$

It follows that

$$\begin{aligned} \Sigma'' &\leq \frac{1}{2} nq \max_{p+1 \leq i \leq n} \|y_i\|_k \leq \frac{nq}{m_{p+1}} \quad (\|y_i\|_k \leq 2/m_i \leq 2/m_{p+1}) \\ &\leq \frac{2n\sqrt{f_{k+1}(m_p)}}{m_{p+1}} \quad \left(q < 2\sqrt{f_{k+1}(m_p)} \right) \\ &\leq \frac{2n}{\sqrt{f_{k+1}(n)}} \leq \frac{2n}{\sqrt{n^8}} = \frac{2}{n^3} \leq \frac{2}{3^3} < \frac{1}{2} \quad (m_{p+1} \geq f_{k+1}(m_p) \geq f_{k+1}(n) \geq n^8). \end{aligned}$$

When $n = 2$, since $k \geq 1$, we have $m_1 = 2$ and $m_2 = f_{k+1}(m_1) \geq f_2(2) = 16$. If $\Sigma'' \neq 0$, then the range of index i in the outer sum defining Σ'' is simply $i = 2 = n = p + 1$, so we may replace nq by q on the first line of the estimate above:

$$\Sigma'' \leq \frac{q}{m_2} < \frac{2\sqrt{m_2}}{m_2} = \frac{2}{\sqrt{m_2}} \leq \frac{2}{\sqrt{16}} = \frac{1}{2},$$

since $m_2 = f_{k+1}(m_1) = f_{k+1}(2) = f_k^{(2)}(2) \geq f_1^{(2)}(2) = 16$.

It follows that

$$\frac{1}{2} \sum_{i=1}^q \|F_i y\|_k \leq 1,$$

and hence $\|y\|_{k+1} \leq 1$. This proves property (3) for $k + 1$, completing the inductive step, and the proof of Theorem 3. \square

4. Proposition. *There exist sequences*

- $(x_i)_{i=1}^{\infty}$ in c_{00} , and
- $(k_j)_{j=1}^{\infty}$ strictly increasing in \mathbb{N} ,

such that

- $\|x_i\|_{k_j} \leq 1/3$ for $j \leq i$,
- $\|x_i\|_{k_j} \geq 2/3$ for $j > i$, and
- $\lim_{j \rightarrow \infty} \|x_i\|_{k_j} = \|x_i\|_T = 1$ for all i .

The proof of Proposition 4 hinges on the following Lemma.

5. Lemma. *Given $k \in \mathbb{N}$, there exist $k' > k$ and $x \in c_{00}$ such that*

$$\|x\|_k \leq 1/3, \quad \|x\|_{k'} \geq 2/3, \quad \|x\|_T = 1.$$

Proof. By Theorem 3 with $n = 12$, given k there exists $y \in c_{00}$ such that $\|y\|_k \leq 1$ and $\|y\|_{k+1} \geq 3$. Since $N := \|y\|_T = \sup_l \|y\|_l \geq \|y\|_{k+1} = 3$, there exists k' with $\|y\|_{k'} \geq \max\{\frac{2}{3}N, 3\}$. The vector $x = y/N$ satisfies:

- $\|x\|_k = \|y\|_k / N \leq 1/N \leq 1/3$,
- $\|x\|_{k'} = \|y\|_{k'} / N \geq \frac{2}{3}N / N = 2/3$, and
- $\|x\|_T = \|y\|_T / N = N / N = 1$.

Since the sequence $(\|x\|_{k_i})_{i=1}^\infty$ is nondecreasing, the first two properties above imply that $k' > k$. \square

Proof of Proposition 4. Given $k \in \mathbb{N}$, let $x_k := x$ and $f(k) := k'$ be those given by Lemma 5. Define a sequence $(k_j)_{j=1}^\infty$ in \mathbb{N} recursively by

- $k_1 = 1$, and
- $k_{j+1} = f(k_j)$ for $j \in \mathbb{N}$,

i.e., $k_j = f^{(j-1)}(1)$. We claim that the sequences $(x_{k_i})_{i=1}^\infty$ and $(k_j)_{j=1}^\infty$ satisfy the properties stated in Proposition 4. Since f is strictly increasing per Lemma 5, so is the sequence (k_j) ; in particular, $k_j \rightarrow \infty$ as $j \rightarrow \infty$. Write $N(i, j)$ for $\|x_{k_i}\|_{k_j}$. By Lemma 5, the monotonicity of the family $\{\|\cdot\|_k\}$ and of the sequence (k_j) , we have

- For $j \leq i$: $N(i, j) \leq N(i, i) \leq 1/3$,
- For $j > i$: $N(i, j) \geq N(i, i+1) \geq 2/3$,
- For all x : $\lim_{j \rightarrow \infty} \|x\|_{k_j} = \|x\|_T$ (since $k_j \rightarrow \infty$ as $j \rightarrow \infty$), and
- For all i : $\|x_i\|_T = 1$. \square

6. Proposition. *There exist sequences $(x_i)_{i=1}^\infty$ in c_{00} , and $(k_j)_{j=1}^\infty$ strictly increasing in \mathbb{N} , such that*

- the limit $\lambda_j := \lim_{i \rightarrow \infty} \|x_i\|_{k_j}$ exists for each $j \in \mathbb{N}$, and
- the limit $\Lambda := \lim_{j \rightarrow \infty} \lambda_j$ exists, satisfies $\Lambda \leq 1/3$, and
- $\lim_{j \rightarrow \infty} \|x_i\|_{k_j} = \|x_i\|_T = 1$ for all $i \in \mathbb{N}$.

Proof. Let $(y_i)_{i=1}^\infty$ in c_{00} and $(l_j)_{j=1}^\infty$ be sequences satisfying the conclusions of Proposition 4. Let $N(i, j) := \|y_i\|_{l_j}$. For fixed j , the sequence $\{N(\cdot, j)\}$ eventually takes values in $[0, 1/3]$; by sequential compactness of $[0, 1/3]$, it has a convergent subsequence, say $\{N(n_{ij}, j)\}_{i=1}^\infty$. The choice of indexes $(n_{ij})_{i=1}^\infty$ realizing the subsequence depends on the fixed choice of j ; we will write n_{ij} instead of n_i in order to exhibit the dependence explicitly. Thus, $\lambda_j := \lim_{i \rightarrow \infty} N(n_{ij}, j)$ exists for each j , and $\lambda_j \leq 1/3$. Let $x_i = y_{n_{ii}}$ for each i , so (x_i) is the ‘‘diagonal’’ subsequence of the family of sequences $\{(y_{n_{ij}})_i : j \in \mathbb{N}\}$. Once more, by sequential compactness, there is a subsequence $(l_{m_j})_{j=1}^\infty$ of (l_j) such that the limit $\Lambda := \lim_{j \rightarrow \infty} \lambda_j$ exists, and necessarily $\Lambda \leq 1/3$. The sequences (x_i) and (k_j) with $k_j = l_{m_j}$ satisfy the following properties: For fixed $j \in \mathbb{N}$, $(n_{ii})_i$ is a subsequence of $(n_{ij})_i$, so

$$\lambda_j = \lim_{i \rightarrow \infty} N(n_{ij}, j) = \lim_{i \rightarrow \infty} N(n_{ii}, j) = \lim_{i \rightarrow \infty} \|x_i\|_{k_j},$$

where the latter (subsequential) limit necessarily exists because $(x_i)_{i=1}^\infty$ is a subsequence of $(y_{n_{ij}})_{i=1}^\infty$. Finally, since (k_j) is a subsequence of (l_j) ,

$$\lim_{j \rightarrow \infty} \|x_i\|_{k_j} = \lim_{j \rightarrow \infty} \|y_{n_{ii}}\|_{l_{m_j}} = \|y_{n_{ii}}\|_T = 1. \quad \square$$

2. FIRST-ORDER NON-DEFINABILITY OF THE TSIRELSON SPACE

2.1. Uniformly Multinormed Structures. Let V be any real vector space endowed with a point-wise bounded collection \mathbf{N} of seminorms, i.e., such that for each $x \in V$ there exists $C \geq 0$ such that $N(x) \leq C$ for all $N \in \mathbf{N}$. The (*concrete*) *uniformly multi-normed (UmN) structure associated to (V, \mathbf{N})* is the structure

$$cM = \langle \mathbf{N}, V_n, 0_n, +_n, \cdot_{t,n}, \iota_{m,n}, \mathbf{Norm}_k : m, n \in \mathbb{N}, m \leq n, t \in \mathbb{R} \rangle,$$

where \mathbf{N} and V_n (for $n \in \mathbb{N}$) are distinct sorts of \mathcal{M} and for all $m \leq n \in \mathbb{N}$:

- $V_n = \{x \in V : N(x) \leq n \text{ for all } N \in \mathbf{N}\}$;
- 0_n is the zero of V ,
- $\iota_{m,n}$ is the inclusion $V_m \hookrightarrow V_n$;
- $+_n$ and $\cdot_{t,n}$ are (the restrictions of) the sum and scalar product-by- t on V to functions $V_n \times V_n \rightarrow V_{2n}$ and $V_n \rightarrow V_l$ where $l = \lceil |tn| \rceil$ (the least integer $\geq |tn|$).
- $\mathbf{Norm}_n(N, x) = N(x)$ for each $N \in \mathbf{N}$ and $x \in V_n$.

The *language for UmN structures* is the first-order (real-valued) language L_{UmN} for general structures whose vocabulary consists of the sorts, constants, functions, and the predicates \mathbf{Norm}_n above.

We shall allow a slightly more general notion of concrete UmN structure, so as to obtain a first-order axiomatizable class (up to canonical identifications³) of general structures in Keisler's sense. We shall only require that $V_1 = \bigcap_{N \in \mathbf{N}} B_N(r_N)$ where, for each $N \in \mathbf{N}$, we have $0 < r_N \leq 1$ and $B_N(r_N)$ is either the open or closed ball of radius r_N relative to the seminorm N (some balls may be open and others closed)⁴ and, accordingly, letting $V_n := nV_1$ for all $n \in \mathbb{N}$. However, in this more general setting, $V' := \bigcup_n V_n$ may be a proper subset of V (in which case, nevertheless, one obtains exactly the same UmN structure from $(V', \mathbf{N} \upharpoonright V')$). Using this more general notion of concrete UmN structure, a given nontrivial (V, \mathbf{N}) typically admits many formally different associated UmN structures (i.e., in different Keisler isomorphism classes).

The first-order theory (in real-valued logic) L_{UmN} -theory of concrete UmN structures is denoted Th_{UmN} . Its models are (*abstract*) *uniformly multinormed (UmN) structures*, and consist of the following:

- A set (sort) \mathbf{N} , called the *norms sort*.
- For all natural numbers m, n :
 - a set (“*sort*”) V_n and an element $0_n \in V_n$;
 - a real-valued predicate \mathbf{Norm}_n on $\mathbf{N} \times V_n$;
 - for every $t \in \mathbb{R}$, a function $\cdot_{t,n} : V_n \rightarrow V_{\lceil |tn| \rceil}$;
 - an operation $+_{n,m} : V_n \times V_m \rightarrow V_{n+m}$;
 - if $n \leq m$, a function $\iota_{n,m} : V_n \rightarrow V_m$;

and are models of Th_{UmN} . Indeed, the zero elements and operations implicitly define a vector space V and a collection \mathbf{N} of seminorms therein (one may construct these explicitly from the direct limit $V := \varinjlim V_n$ —relative to the identifications $\iota_{m,n}$ —with operations $+$ and \cdot induced by the operations $+_{n,m}$ and $\cdot_{t,n}$, plus one seminorm corresponding to each element $N \in \mathbf{N}$ —it is induced by the functions $\mathbf{Norm}_n(N, \cdot)$ as n varies). The theory of UmN structures is necessary and sufficient to ensure that V_1 is the intersection of open or closed balls (in the seminorms $N \in \mathbf{N}$) of radii at most 1.

³See Remarks 7

⁴The sorts V_n first described above are obtained when the balls $B_N(1)$ are all of radius $r_N = 1$ and closed.

7. **Remarks.** (1) Whenever sensible, if \mathcal{M} is an UmN structure, N an element of $\mathbf{N}^{\mathcal{M}}$, and $x \in V_n^{\mathcal{M}}$, we write $N(x)$ as an alias for the syntactically clumsy $\mathbf{Norm}_n^{\mathcal{M}}(N, x)$.
- (2) If \mathcal{M} is a concrete UmN structure obtained, so is its *reduction* $\mathcal{M}_{\text{Red}} := \mathcal{M}/\equiv$ obtained under identification of elements of each $V_n^{\mathcal{M}}$ by the equivalence relation

$$x \equiv y \quad \Leftrightarrow \quad N(y - x) = 0 \text{ for all } N \in \mathbf{N}^{\mathcal{M}},$$

and the correspondingly induced operations and interpretations of the Norm predicates. Moreover, \mathcal{M} and \mathcal{M}_{Red} isomorphic in Keisler's sense, although we prefer to say that they are in the same isomorphism class (one of the peculiarities of the theory of general classes is that there need not exist a bijective isomorphism between the universes of \mathcal{M} of \mathcal{M}_{Red} —the quotient maps $a \mapsto a/\equiv$ from the universe of \mathcal{M} onto the universe of \mathcal{M}_{Red} need not be injective).

In summary, every UmN structure is concrete, up to reduction and isomorphism.

Although the technical definition of UmN structures is needed to apply the Keisler formalism to spaces endowed with multiple norms, the preceding remarks essentially allow abstracting the sorts V_n and regard a uniformly multinormed structure \mathcal{M} as a “metastructure” $\mathcal{M}^* = \langle V, 0, +, \cdot, \mathbf{N}, \mathbf{Norm} \rangle$ with a single vector sort $V = \bigcup_n V_n$ with zero 0, operations $+$ and \cdot , and \mathbf{N} a set of formal names (labels) for seminorms on \mathbf{N} realized via the single predicate \mathbf{Norm} (the latter ingredients of \mathcal{M}^* are naturally induced from those of \mathcal{M}). A critical feature of the metapredicate $\mathbf{Norm}^{\mathcal{M}}$ is its local boundedness on $V^{\mathcal{M}}$ (actually, $\mathbf{Norm}^{\mathcal{M}}(N, \cdot) \leq 1$ on $V_1^{\mathcal{M}}$ for all $N \in \mathbf{N}^{\mathcal{M}}$) as alluded by the adverb “uniformly” (although $\mathbf{Norm}^{\mathcal{M}}(N, \cdot)$ is typically unbounded on all of $V^{\mathcal{M}}$).

In what follows, we mostly pretend away the technicalities of the multisorts V_n , and treat UmN metastructures in the above sense as though they are *bona fide* Keisler general structures. In particular, we shall treat UmN structures as concrete ones (with $V_k \subseteq V_l$ for $k \leq l$, in particular). The phenomenon that many different (say, concrete) UmN structures may yield the same metastructure hints at an external notion of isomorphism classes (i.e., isomorphism classes of \equiv -reduced UmN metastructures) typically larger than Keisler isomorphism classes. However, we shall not pursue this avenue of research presently as it is not relevant to the considerations of this manuscript. Still, when the multisorted nature of UmN structures is obscured by the metastructural viewpoint, we shall comment accordingly.

8. **Remarks.**
- The peculiar sort \mathbf{N} whose elements formally name seminorms on V (rather than the seemingly more natural viewpoint of regarding each individual seminorm as a predicate) allows us to use the theory of stability and definability of types to study norms regarded as objects in the universe of the (meta)structure.
 - Given a UmN structure \mathcal{M} (say, concrete, at least for purposes of exposition) and any collection S of seminorms on $V^{\mathcal{M}}$ such that $N(x) \leq 1$ for all $N \in S$ and $x \in V_1^{\mathcal{M}}$, one obtains an elementary extension $\widetilde{\mathcal{M}} \geq \mathcal{M}$ by keeping the same vector sort $V^{\widetilde{\mathcal{M}}} := V^{\mathcal{M}}$, letting $\mathbf{N}^{\widetilde{\mathcal{M}}} := S \sqcup \mathbf{N}^{\mathcal{M}}$, and extending $\mathbf{Norm}^{\mathcal{M}}$ to $\mathbf{N}^{\widetilde{\mathcal{M}}} \times V^{\widetilde{\mathcal{M}}}$ by $\mathbf{Norm}^{\mathcal{M}}(N, x) := N(x)$ for $N \in S$ and $x \in V^{\widetilde{\mathcal{M}}}$.

For the rest of this section, \mathcal{M} will be a fixed multi-normed structure associated to (V, \mathbf{N}) (thus V is a real vector space and \mathbf{N} is a pointwise bounded collection of seminorms on V) and we will maintain all the notational conventions introduced in this subsection.

2.2. Types and Definability in UmN Structures. For our applications, we shall focus exclusively on *mixed-sort types* in UmN structures; these types describe potential properties of object(s) of one sort (V vs. \mathbf{N}) in terms of parameters in the other sort.

Fix a formula $\varphi(\bar{N}; \bar{z})$ on an m -tuple \bar{N} of formal variables of sort \mathbf{N} , and an n -tuple \bar{z} of variables of sort V . Given an UmN-structure \mathcal{M} and a set $A \subseteq V^{\mathcal{M}}$, the φ -type of $\bar{N} \in (\mathbf{N}^{\mathcal{M}})^m$ (with parameters in A) is the function

$$\begin{aligned} \varphi_N^{\mathcal{M}} : A^n &\rightarrow \mathbb{R} \\ (x_1, \dots, x_n) &\mapsto \varphi^{\mathcal{M}}(\bar{N}; x_1, \dots, x_n). \end{aligned} \tag{2.1}$$

The notion of $\tilde{\varphi}$ -types, which are dual to the φ -types above, is obtained by formally exchanging the roles of the variables \bar{N} and \bar{x} , i.e., $\tilde{\varphi}$ types are types for the formula $\tilde{\varphi}(\bar{x}; \bar{N}) \equiv \varphi(\bar{N}; \bar{x})$. Explicitly, the $\tilde{\varphi}$ -type of the n -tuple \bar{x} of elements of the universe $V^{\mathcal{M}}$ of an L_{Nseq} -structure \mathcal{M} , with parameters in $B \subseteq \mathbf{N}^{\mathcal{M}}$, is the function

$$\begin{aligned} \tilde{\varphi}_{\bar{x}} : B^n &\rightarrow \mathbb{R} \\ \bar{N} &\mapsto \varphi^{\mathcal{M}}(\bar{N}; \bar{x}). \end{aligned}$$

The φ -type of a tuple $\bar{N} \in (\mathbf{N}^{\mathcal{M}})^m$ is said to be *realized* in \mathcal{M} . The collection of these is denoted $\mathcal{P}_{\varphi}^{\mathcal{M}}(A)$, where $A \subseteq V^{\mathcal{M}}$ is the set of parameters of these types. The collection $\mathcal{S}_{\varphi}(A)$ of all φ -types (with parameters in A) consists of the types of all m -tuples \bar{N} of elements of sort \mathbf{N} in all elementary extensions $\langle \tilde{\mathcal{M}}, a : a \in A \rangle \geq \langle \mathcal{M}, a : a \in A \rangle$. The set $\mathcal{S}_{\varphi}(A)$ inherits the subspace topology from the product space \mathbb{R}^{A^n} . The formally multisorted nature of (the metasort) V implies that $A \subseteq V_k^{\mathcal{M}}$ for some $k \in \mathbb{N}$, and furthermore $\mathcal{S}_{\varphi}(A)$ is compact (by logical compactness).⁵ These considerations translate *mutatis mutandis* to the sets $\mathcal{S}_{\tilde{\varphi}}(B)$ of all dual types (realized in a fixed model \mathcal{M} , in the case of $\mathcal{P}_{\tilde{\varphi}}^{\mathcal{M}}(B)$).⁶

2.2.1. Semidefinable Global Predicates and Definable Types. Fix a formula $\varphi(\bar{N}; \bar{x})$. Throughout this section \mathcal{M} is an arbitrary L_{UmN} -structure and (\bar{N}_k) is a fixed sequence of m -tuples in $\mathbf{N}^{\mathcal{M}}$. The *global $\tilde{\varphi}$ -predicate P of kind V^n semidefined by the ultrafilter $\mathcal{U} \in \beta\mathbb{N}$ and (\bar{N}_k)* is the class of all real-valued functions

$$\begin{aligned} P^{\tilde{\mathcal{M}}} : (V^{\tilde{\mathcal{M}}})^n &\rightarrow \mathbb{R} \\ \bar{x} &\mapsto \lim_{\mathcal{U}, k} \varphi^{\tilde{\mathcal{M}}}(\bar{N}_k; \bar{x}) \end{aligned}$$

as $\tilde{\mathcal{M}}$ ranges over elementary extension of \mathcal{M} . Concretely, each $P^{\tilde{\mathcal{M}}}$ is obtained in all $\tilde{\mathcal{M}} \geq \mathcal{M}$ as the *same* ultralimit of the sequence $(\varphi_{\bar{N}_k}^{\tilde{\mathcal{M}}})$ of types realized in \mathcal{M} .

A semi-definable global $\tilde{\varphi}$ -predicate P is *definable over a set of parameters $B \subseteq \mathbf{N}^{\mathcal{M}}$* if $P^{\tilde{\mathcal{M}}}$ is equal to the uniform limit of some sequence of types (with parameters in $V^{\tilde{\mathcal{M}}}$) that are realized in \mathcal{M} (though not necessarily of φ -types). More concretely, P is indeed so definable precisely if

⁵Formally, the variables in the tuple \bar{x} are necessarily of sort V_k for some k , so φ *sensu stricti* only involves parameters on $A \subseteq V_k^{\mathcal{M}}$ for (any) such k . On the other hand, since sort \mathbf{N} is discrete by definition, the parameter set $B \subseteq \mathbf{N}^{\mathcal{M}}$ is otherwise completely arbitrary.

⁶The spaces of dual types *a priori* each consist of types $\tilde{\varphi}_{\bar{x}}$ with \bar{x} of sort V^k for some k depending only on $\tilde{\varphi}$ itself.

each $P^{\widetilde{\mathcal{M}}}$ is obtained as the same continuous combination of the collection $\langle \varphi_{\overline{N}}^{\widetilde{\mathcal{M}}} : \overline{N} \in B^m \rangle$, i.e., if there exists a continuous function $C : \mathbb{R}^{B^m} \rightarrow \mathbb{R}$ such that

$$P^{\widetilde{\mathcal{M}}}(\overline{x}) = C(\langle \varphi(\overline{N}; \overline{x})^{\mathcal{M}} : \overline{N} \in B^m \rangle) \quad \text{for all } \overline{x} \in (V^{\widetilde{\mathcal{M}}})^n.$$

A type $p \in S_{\varphi}^{\mathcal{M}}$ is (semi)definable over a set of parameters B if there exists a (semi)definable global $\tilde{\varphi}$ -predicate P_p over B such that

$$p(\overline{x}) = P_p^{\mathcal{M}}(\overline{x}) \quad \text{for all } \overline{x} \in (V^{\mathcal{M}})^n. \quad (2.2)$$

Such predicate P_p defines p .

9. Remark. A definable $\tilde{\varphi}$ -predicate P over \mathcal{M} admits an extension to a continuous function $S_{\tilde{\varphi}}^{\mathcal{M}} \rightarrow \mathbb{R}$, which we also call P by an abuse of notation. Via its definition P_p , a definable φ -type p over \mathcal{M} admits a natural extension to a continuous function on $S_{\tilde{\varphi}}^{\mathcal{M}}$. For details on definability and stability in the context of real-valued logic, the reader is referred to the literature [BYU10, BY14, Kei23].

2.2.2. Norm-Sequence Structures. The language L_{Nseq} for norm sequences expands L_{UmN} with constant symbols (of the approximant norms) $\|\cdot\|_k$ ($k \in \mathbb{N}$) and $\|\|\cdot\|\|$ (the symbol for the master norm) of sort \mathbf{N} .

We shall use the syntactic aliases $\|x\|_k$ (resp., $\|\|x\|\|$) for $\mathbf{Norm}(\|\cdot\|_k, x)$ (resp., for $\mathbf{Norm}(\|\|\cdot\|\|, x)$). The function $x \mapsto \mathbf{Norm}^{\mathcal{M}}(\|\cdot\|_k^{\mathcal{M}}, x)$ on $V^{\mathcal{M}}$ will be denoted $\|\cdot\|_k^{\mathcal{M}}$ (or just $\|\cdot\|_k$, if \mathcal{M} is clear), and similarly for $\|\|\cdot\|\|$ ($= \|\|\cdot\|\|^{\mathcal{M}}$).

Given an Nseq structure \mathcal{M} and an n -tuple \overline{x} elements of the vector sort of \mathcal{M} , by formally identifying $\|\cdot\|_k$ with its index k , the $\tilde{\varphi}$ -type $\tilde{\varphi}_{\overline{x}}$ —with parameters in the collection $\mathbf{N}_{\mathbb{N}}^{\mathcal{M}} := \{\|\cdot\|_k^{\mathcal{M}} : k \in \mathbb{N}\}$ of approximant norms—is a bounded real sequence $(t_k)_{k \in \mathbb{N}}$, $t_k = \varphi^{\mathcal{M}}(\|\cdot\|_k; \overline{x})$. Accordingly, we may regard $S_{\tilde{\varphi}}^{\mathcal{M}}(\mathbf{N}_{\mathbb{N}}^{\mathcal{M}})$ as a topological subspace of $\mathbb{R}^{\mathbb{N}}$ (with the product topology, i.e., the topology of pointwise convergence).

10. Remarks. An Nseq structure may have additional functions, constants, predicate interpretations, and possibly even other sorts. However, as long as the vocabulary $L \supseteq L_{\text{Nseq}}$ for such a structure is fixed and countable, Keisler’s Expansion Theorem for general such L -structures implies that any L -theory T has a pre-metric expansion with a pseudo-metric approximate distance d . Although d is not canonical, the metric topology induced in models of T is. Thus, models of such a theory T are (multisorted) metric spaces, up to canonical reduction and metric equivalence.

For structures with the exact vocabulary L_{Nseq} and any L_{Nseq} -theory T including the sentences $\sup_{x \in V_k} \mathbf{Norm}_k(\|\cdot\|_n, x) \leq \sup_{x \in V_k} \mathbf{Norm}_k(\|\|\cdot\|\|, x)$ for $k, n \in \mathbb{N}$, one may regard the sort \mathbf{N} as a discrete space, and the sorts V_k as metrized by $d(x, y) := \|\|y - x\|\|$ in models of T . Thus, for Tsirelson and Schlumprecht structures as defined below, the formalism of metric structures *à la* Ben Yaacov-Berenstein-Henson-Usvyatsov [BYU10, BYBHU08] suffices for our purposes.

2.3. Tsirelson Structures. The classical Tsirelson structure \mathcal{T} is the L_{Nseq} structure obtained from Tsirelson’s space \mathcal{T} , with $\|\cdot\|_k$ interpreted as the k -th Tsirelson approximant, and $\|\|\cdot\|\|$ interpreted as the Tsirelson norm (via the \mathbf{Norm} predicate, of course).

A Tsirelson structure is a model \mathcal{M} of $\text{Th}_{\mathcal{T}}$, the L_{Nseq} -theory of the classical Tsirelson structure \mathcal{T} . In general, the \mathbf{N} -sort $\mathbf{N}^{\mathcal{M}}$ of a Tsirelson structure \mathcal{M} contains elements not named by the symbols $\|\|\cdot\|\|$, $\|\cdot\|_k$ (see Remark 10). However, any element $N \in \mathbf{N}^{\mathcal{M}}$ whatsoever still serves as the name of a seminorm $x \mapsto N(x) := \mathbf{Norm}(N, x)$ on the vector sort $V^{\mathcal{M}}$. $\text{Th}_{\mathcal{T}}$ also ensures that $N(\cdot) \leq \|\|\cdot\|\|^{\mathcal{M}}$ everywhere.

In every Tsirelson structure \mathcal{M} we define the (external) *Tsirelson norm* $\|\cdot\|_T^{\mathcal{M}}$ on \mathcal{M} in the obvious way, namely

$$\|x\|_T^{\mathcal{M}} := \lim_{k \rightarrow \infty} \|x\|_k^{\mathcal{M}} \quad \text{for all } x \in V^{\mathcal{M}}. \quad (2.3)$$

The existence (and finiteness!) of the limit in (2.3) follows from the observation that \mathcal{M} is a model of $\text{Th}_{\mathcal{T}}$, which includes the sentences $(\forall x \in V_1)(\|x\|_k \leq \|x\|_l \leq \| \|x\| \|)$ for $k < l \in \mathbb{N}$, since these are true in the classical Tsirelson space \mathcal{T} where $\| \cdot \|_{\mathcal{T}}$ coincides with $\| \cdot \|_T^{\mathcal{T}}$. Thus, for all $x \in V_1^{\mathcal{M}}$ (and, by linearity, for all $x \in V^{\mathcal{M}}$),

$$\|x\|_T^{\mathcal{M}} = \lim_{k \rightarrow \infty} \|x\|_k^{\mathcal{M}} = \sup_{k \in \mathbb{N}} \|x\|_k^{\mathcal{M}} \leq \| \|x\| \|_{\mathcal{M}} < \infty.$$

However, there is no *a priori* reason for $\|\cdot\|_T^{\mathcal{M}}$ to coincide with $\| \cdot \|_{\mathcal{M}}$ in arbitrary Tsirelson structures (see Remark 11 below).

From its construction, one may regard $\|\cdot\|_T^{\mathcal{M}}$ as a real-valued predicate on $V^{\mathcal{M}}$. On the other hand, letting the Tsirelson norm $\|\cdot\|_T^{\mathcal{M}}$ may also be regarded as a *Norm*-type (i.e., a type for the formula $\text{Norm}(N, x)$). In fact, $\|\cdot\|_T^{\mathcal{M}}$ is a *semidefinable limit* of the types $\text{Norm}_{\|\cdot\|_k^{\mathcal{M}}}$ in the sense that it is an accumulation point (equivalently, an ultralimit⁷) of the set of these types.

11. Remarks. A model \mathcal{M} of $\text{Th}_{\mathcal{T}}$ is elementarily equivalent to the classical Tsirelson space \mathcal{T} . However, we emphasize that $\|\cdot\|_T^{\mathcal{M}}$ is not part of the structure \mathcal{M} , but only defined externally: The non-definability of the Tsirelson norm (as captured in Theorem 14 below) implies that the interpretation $\| \cdot \|_{\mathcal{M}}$ in such a model \mathcal{M} need not coincide with the (external) pointwise limit $\|\cdot\|_T^{\mathcal{M}} := \lim_{k \rightarrow \infty} \|\cdot\|_k^{\mathcal{M}}$.

To conform to the multisorted framework, the formula φ underlying the *Norm*-types will be, strictly speaking, the formula $\text{Norm}_1(N, x)$ (with N of kind \mathbf{N} and x of kind V_1) when issues of boundedness play a role in subsequent discussions.

2.4. Non-Definability of the Tsirelson Norm.

12. Theorem. *The Tsirelson norm is not stable in the classical Tsirelson space \mathcal{T} . More precisely, there exist:*

- a sequence $\{x_i : i \in \mathbb{N}\}$ in Tsirelson's space, and
- a sequence $\{\|\cdot\|_{k_j} : j \in \mathbb{N}\}$ of approximants to the Tsirelson norm $\|\cdot\|_T$,

such that

$$\lim_{i \rightarrow \infty} \|x_i\|_T = \lim_{i \rightarrow \infty} \lim_{j \rightarrow \infty} \|x_i\|_{k_j} \neq \lim_{j \rightarrow \infty} \lim_{i \rightarrow \infty} \|x_i\|_{k_j}, \quad (2.4)$$

where all limits involved exist and are finite.

Proof. With $\{x_i\}$ and $\{k_j\}$ chosen so the conclusions of Proposition 6 hold, all limits in the statement of Theorem 12 exist, and

$$1 = \lim_{i \rightarrow \infty} \|x_i\|_T = \lim_{i \rightarrow \infty} \lim_{j \rightarrow \infty} \|x_i\|_{k_j},$$

but

$$\lim_{j \rightarrow \infty} \lim_{i \rightarrow \infty} \|x_i\|_{k_j} \leq 1/3. \quad \square$$

13. Proposition. *Given a structure \mathcal{M} , the following properties are equivalent:*

- (1) A formula φ is stable over a structure \mathcal{M} .

⁷In fact, $\|\cdot\|_T^{\mathcal{M}}$ is the *unique* such limit point (ultralimit) when \mathcal{M} models $\text{Th}_{\mathcal{T}}$.

- (2) If a φ -type $p \in S_\varphi(\mathcal{M})$ is an accumulation point of a sequence $(p_i)_{i=1}^\infty$ of φ -types realized in \mathcal{M} , then p is definable over \mathcal{M} , and there exists a subsequence $(p_{i_j})_{j=1}^\infty$ whose φ -types converge point-wise on $S_\varphi(\mathcal{M})$ to a definition of p .

Furthermore, if such is the case, then every φ -type is a pointwise limit (i.e., a limit in the logic topology) of realized types: $S_\varphi^\mathcal{M} = \overline{\mathcal{P}_\varphi^\mathcal{M}}$.

Proof. The assertion is a particular case of the equivalence between properties (i) and (iii) in [BY14, Theorem 5]. \square

14. Theorem (First-Order Non-Definability of the Tsirelson Norm). *The Tsirelson norm $\|\cdot\|_T^\mathcal{M}$ is not definable over L_{Nseq} -structures \mathcal{M} that satisfy either of the following properties:*

- \mathcal{M} is an elementary extension of the classical Tsirelson space \mathcal{T} , or
- \mathcal{M} is a countably saturated model of $\text{Th}_\mathcal{T}$.

Proof. As shown in section 2.3, $\text{Th}_\mathcal{T}$ implies that the Tsirelson norm (2.3) is the only global type semidefinable over the sequence of types $\mathbf{Norm}_k := \|\cdot\|_k$ of the approximant norms (independently of the choice of $\mathcal{U} \in \beta\mathbb{N}$).⁸ In particular, the Tsirelson norm is the only accumulation point of any sequence $(\|\cdot\|_{k_i})_{i=1}^\infty$ of the \mathbf{Norm} -types of the approximant norms.

Assume first that \mathcal{M} is an elementary extension of \mathcal{T} . By Theorem 12, \mathbf{Norm} is not stable in \mathcal{T} , hence neither in $\mathcal{M} \geq \mathcal{T}$; thus, by Proposition 13, the Tsirelson norm is not definable over \mathcal{M} , but we can be more specific. With (x_i) and (k_j) as in Theorem 12, let \mathcal{U} be any nonprincipal ultrafilter on \mathbb{N} , and let $q = \lim_{i,\mathcal{U}} \mathbf{Norm}_{x_i}^\sim$ be the \mathcal{U} -ultralimit type of the realized dual types of (x_i) . If $\|\cdot\|_T^\mathcal{M}$ were definable, then it would be equal to the pointwise limit of the types $\|\cdot\|_{l_j}$ for some subsequence (l_j) of (k_j) , and the value (of the extension to dual types⁹) of $\|\cdot\|_T$ at q would be $\lambda := \lim_{j \rightarrow \infty} \xi_{l_j}(q) = \lim_{j \rightarrow \infty} \lim_{i,\mathcal{U}} \|x_i\|_{l_j} = \lim_{j \rightarrow \infty} \lim_{i \rightarrow \infty} \|x_i\|_{k_j}$ (since the latter limits exist and equal the respective subsequential limit and ultralimit). On the other hand, again by definability, $\|\cdot\|_T$ would be a continuous function on dual types, so its value at $q = \lim_{i,\mathcal{U}} \mathbf{Norm}_{x_i}^\sim$ would equal $\rho := \lim_{i,\mathcal{U}} \|q\|_T^\mathcal{M} = \lim_{i,\mathcal{U}} \|x_i\|_T^\mathcal{M} = \lim_{i \rightarrow \infty} \lim_{k \rightarrow \infty} \|x_i\|_k^\mathcal{M} = \lim_{i \rightarrow \infty} \lim_{j \rightarrow \infty} \|x_i\|_{k_j}^\mathcal{M}$. However, $\lambda \neq \rho$ per Theorem 12. Thus, in the sense explained, the dual type q witnesses the non-definability of $\|\cdot\|_T^\mathcal{M}$.

Next, let \mathcal{M} be a countably saturated model of $\text{Th}_\mathcal{T}$. Consider the full dual type q (in a countable tuple $\bar{z} = (z_i)_{i=1}^\infty$ of variables) of the sequence $\bar{x} = (x_i)_{i=1}^\infty$ in $V_1^\mathcal{T}$ above. This full dual type is the collection $(\tilde{\varphi}_{\bar{x}} : \varphi \in \Phi)$ of all dual types $\tilde{\varphi}_{\bar{x}} = \varphi(\cdot; \bar{x})$ as $\varphi(N; \bar{z})$ varies over the collection Φ of all L -formulas in which only finitely many of the variables z_i appear free. The dual types $\varphi_{\bar{x}}$ considered here are functions on the collection $\{\|\cdot\|^\mathcal{T}\} \cup \{\|\cdot\|_k^\mathcal{T}\}_{k=1}^\infty$ of all interpretations of the norm symbol N in \mathcal{T} (rather than functions defined only on the collection of norms $\|\cdot\|_k^\mathcal{T}$).¹⁰ Since q is a type on countably many variables, countable saturation of \mathcal{M} ensures that it is realized by a sequence $\bar{y} = (y_i)_{i=1}^\infty$ in $V^\mathcal{M}$. For ease of exposition, let us assume that (x_i) and (k_j) were chosen with the properties stated in Proposition 4. For each i , the element y_i satisfies¹¹

⁸Recall that the relevant types and predicates are relative to the formula $\mathbf{Norm}_1(N, x)$ with x of sort V_1 . The present use of the subindex k in \mathbf{Norm}_k should cause no confusion.

⁹See Remark 9

¹⁰In \mathcal{T} , the interpretation $\|\cdot\|^\mathcal{T}$ of the master norm is the Tsirelson norm $\|\cdot\|_T^\mathcal{T}$, but this need not hold in the model \mathcal{M} . (See Remark 11).

¹¹However, the external Tsirelson norm $\|\cdot\|_T^\mathcal{M}$ need not equal $\|\cdot\|_T^\mathcal{T} = \|x_i\|_T^\mathcal{T} = 1$.

- $\|y_i\|_{k_j} \leq 1/3$, if $j \leq i$,
- $\|y_i\|_{k_j} \geq 2/3$, if $j > i$, and
- $\|y_i\|_{k_j}^{\mathcal{M}} = 1$,

since the corresponding properties of x_i are translated to an equality (or inequality) satisfied by the dual type $\mathbf{Norm}_{x_i}^{\sim} \in q$ at the points $N = \|\cdot\|^{\mathcal{M}}$ (or $N = \|\cdot\|_{k_j}^{\mathcal{M}}$), and y_i realizes q . $\text{Th}_{\mathcal{T}}$ ensures that, in models \mathcal{M} thereof, the interpretations of the norms satisfy $\|\cdot\|_k^{\mathcal{M}} \leq \|\cdot\|_l^{\mathcal{M}} \leq \|\cdot\|^{\mathcal{M}}$ pointwise for $k \leq l$. In particular, $\|\cdot\|_T^{\mathcal{M}}$ is (finite) and everywhere defined on $V^{\mathcal{M}}$. In fact

$$\|y_i\|_T^{\mathcal{M}} = \lim_{j \rightarrow \infty} \|y_i\|_{k_j}^{\mathcal{M}} = \sup_k \|y_i\|_k^{\mathcal{M}} \leq \|y_i\|^{\mathcal{M}} = 1.$$

On the one hand, for all $i \in \mathbb{N}$, we have

$$\|y_i\|_T^{\mathcal{M}} \geq \|y_i\|_{k_{i+1}}^{\mathcal{M}} \geq 2/3,$$

hence

$$\lim_{i \rightarrow \infty} \lim_{j \rightarrow \infty} \|y_i\|_{k_j} = \lim_{i \rightarrow \infty} \|y_i\|_T^{\mathcal{M}} \geq 2/3.$$

Furthermore, for fixed $j \in \mathbb{N}$, the sequence $\{\|y_i\|_{k_j}\}_{i=1}^{\infty}$ takes values $\leq 1/3$ for $i \geq j$; thus, $\lim_{i \rightarrow \infty} \|y_i\|_{k_j} \leq 1/3$, and hence

$$\lim_{j \rightarrow \infty} \lim_{i \rightarrow \infty} \|y_i\|_{k_j} \leq 1/3.$$

This shows that the formula \mathbf{Norm} is not stable in \mathcal{M} , and we conclude that the Tsirelson norm is not definable over \mathcal{M} , by Theorem 12. \square

3. SCHLUMPRECHT'S SPACE

3.1. Construction of the Schlumprecht space. The construction of Schlumprecht's space is similar to that of Tsirelson's. We use the same notation as in section 1, except for the requirement that admissible families of finitely many nonempty finite subsets, say E_i ($1 \leq i \leq m$) of \mathbb{N} need only satisfy $E_1 < E_2 < \dots < E_m$ (and not necessarily the requirement $E_1 \geq m$ as in Tsirelson's construction). Let $L(t) = \log_2(t+1)$ and $\mathfrak{L}(t) = t/L(t)$ for $t > 0$. It is trivial to verify that both L and \mathfrak{L} are unbounded and strictly increasing.

Define the sequence $\{\|\cdot\|_k\}_{k=0}^{\infty}$ of norms on c_{00} (the *Schlumprecht approximants*) recursively as follows. For $x = \sum_n a_n e_n \in c_{00}$,

$$\|x\|_0 := \|x\|_{\ell_{\infty}} = \max_n |a_n|,$$

and, for $k \geq 1$,

$$\|x\|_k = \max \left\{ \frac{1}{L(m)} \sum_{i=1}^m \|E_i x\|_{k-1} : E_1 < E_2 < \dots < E_m \right\},$$

where the maximum is taken over the set of all admissible collections of any size $m \geq 1$. (The reuse of the notation $\|\cdot\|_k$ is convenient, but unrelated to the Tsirelson norms introduced in section 1.1.) Since $L(1) = 1$, we see that the inequality $\|x\|_k \geq \|x\|_{k-1}$ holds for all $x \in c_{00}$ and $k \geq 1$, as witnessed by the singleton collection $\{E_1\}$, where $E_1 = \text{supp}(x)$. The *Schlumprecht norm* of $x \in c_{00}$ is defined by

$$\|x\| = \lim_{k \rightarrow \infty} \|x\|_k \quad (= \sup_{k \in \mathbb{N}} \|x\|_k),$$

and *Schlumprecht's space* \mathcal{S} is the norm-completion of $(c_{00}, \|\cdot\|_{\mathcal{S}})$. The induced norm on \mathcal{S} is still denoted $\|\cdot\|_{\mathcal{S}}$ by an abuse of notation. Routine induction shows that $\|x\|_k \leq \sum_n |a_n| = \|x\|_{\ell_1}$ for $x \in c_{00}$ and $k \in \mathbb{N}$. Thus, inequality $\|x\|_{\mathcal{S}} \leq \|x\|_{\ell_1}$ also holds for all $x \in c_{00}$ *a priori* and, *a posteriori*, for all $x \in \mathcal{S}$.

Evidently, the Schlumprecht approximants and the Schlumprecht norms depend only on the absolute values of the coefficients, and monotonically so.

In contrast to Tsirelson's construction, the admissibility condition for families $\{E_i\}$ in Schlumprecht's case is invariant under the shift-by- j transformation $\sum_i a_i e_i \mapsto \sum_i a_i e_{i+j}$ for any fixed $j \geq 0$. Since $\|\cdot\|_0 = \|\cdot\|_{\ell_\infty}$ is also shift-invariant, it follows inductively that all approximants $\|\cdot\|_k$ are shift-invariant, and so is the Schlumprecht norm $\|\cdot\|_{\mathcal{S}}$ itself.¹²

3.2. Non-uniform convergence of the Schlumprecht approximants.

3.2.1. Auxiliary sequences of rapid growth.

15. Definition. Let L^* , \mathfrak{L}^* be the integer-valued quasi-inverses of L , \mathfrak{L} , namely, for $n \in \mathbb{N}$,

$$\begin{aligned}\mathfrak{L}^*(n) &= \lceil \mathfrak{L}^{-1}(n) \rceil = \min\{m \in \mathbb{N} : m / \log_2(m+1) \geq n\}; \\ L^*(n) &= L^{-1}(n) = 2^n - 1 \quad (= \min\{m \in \mathbb{N} : \log_2(m+1) \geq n\}).\end{aligned}$$

16. Proposition. *Given any function $M : \mathbb{N} \rightarrow \mathbb{N}$, there exist unique functions*

$$\begin{aligned}\Lambda &: (k, n) \mapsto \Lambda_k(n) \quad (k, n \geq 1) \\ \lambda &: (k, n, i) \mapsto \lambda_k^i(n) \quad (k, n, i \geq 1) \\ \nu &: (k, n, i) \mapsto \nu_k^i(n) \quad (k \geq 2 \ \& \ n, i \geq 1)\end{aligned}$$

taking values in \mathbb{N} such that the following identities hold:

- (1) $\lambda_1^1(n) = 1$;
- (2) $\lambda_1^{i+1}(n) = L^*(2L[\lambda_1^i(n)]) = [1 + \lambda_1^i(n)]^2 - 1$;
- (3) $\lambda_k^i(n) = \Lambda_{k-1}[2^i \nu_k^i(n)] \quad (k \geq 2)$;
- (4) $\Lambda_k(n) = \sum_{i=1}^{M(n)} \lambda_k^i(n)$;
- (5) $\nu_k^1(n) = 2 \quad (k \geq 2)$;
- (6) $\nu_k^{i+1}(n) = L^*(2^i L[\lambda_k^i(n)]) = [1 + \lambda_k^i(n)]^{2^i} - 1 \quad (k \geq 2)$.

If M is strictly increasing then each of the functions λ , Λ , μ is increasing in each variable separately (strictly increasing indeed—apart from the equalities $\lambda_1^1(n) = 1$ and $\nu_k^1(n) = 2$ for all $k \geq 2$ and $n \geq 1$).

Proof. The existence and uniqueness of Λ , λ and ν are immediate, since the given conditions amount to a jointly recursive definition thereof. The asserted monotonicity of λ , Λ , μ conditional on M being strictly increasing is trivially verified. \square

For $k, n, i \geq 1$, define

$$\begin{aligned}\lambda_k^{\leq 0}(n) &= 0, \quad \text{and} \\ \lambda_k^{\leq i}(n) &= \sum_{j=1}^i \lambda_k^j(n).\end{aligned}$$

¹²More generally, the Schlumprecht norm is invariant under monotone re-indexing transformations $\sum_i a_i e_i \mapsto \sum_i a_i e_{j_i}$ via any fixed choice of strictly increasing indexes $1 \leq j_1 < j_2 < \dots < j_i < \dots$.

(In particular, $\Lambda_k(n) = \lambda_k^{\leq M(n)}(n)$ for $k \geq 1$.)

3.2.2. The main proposition.

17. Proposition. *There exist unique vectors $Z(l)$, $X_k(n)$, $Y_k(n)$ and $x_k^i(n)$ ($k, l, n, i \geq 1$) in c_{00} such that*

- (1) $Z(l) = \frac{1}{\mathfrak{Q}(l)} \sum_{i=1}^l e_i$;
- (2) $X_k(n) = Y_k(n) / \|Y_k(n)\|_{k+1}$;
- (3) $Y_k(n) = D \sum_{i=1}^{M(n)} x_k^i(n)$;
- (4) $x_1^i(n) = Z(\lambda_1^i(n))$; and
- (5) $x_k^i(n) = X_{k-1}(2^i v_k^i(n))$ ($k \geq 2$);
- (6) The support of $Y_k(n)$ is $I_k(n) := [1, \Lambda_k(n)]$;
- (7) The support of $x_k^i(n)$ is $[1, \lambda_k^i(n)]$, and the coefficients of $x_k^i(n)$ in the direct sum (3) fill the interval $I_k^i(n) := (\lambda_k^{\leq i-1}(n), \lambda_k^{\leq i}(n)]$ in $Y_k(n)$, and also in $X_k(n)$;
- (8) $\|x_k^i(n)\|_k = 1$;
- (9) $\|Y_k(n)\|_k \leq 3$; and
- (10) $\|Y_k(n)\|_{k+1} \geq 3n$.

To begin the proof of Proposition 17, note first that conditions (1)–(5) amount to a (unique) recursive definition of all the required vectors.

Properties (6) and (7) are proved simultaneously by induction on k (and, for k fixed, by induction on i). The details are trivial and omitted.

We prove that (8), (9) and (10) hold, for all $n \geq 2$ and $i \geq 1$, by induction on $k \geq 1$. Throughout the proof, we write M for $M(n)$.

3.2.3. The base of the induction. The proof for $k = 1$ is as follows. We will presently write $Y(n)$, I_j , x_j , λ_j for $Y_1(n)$, $I_1^j(n)$, $x_1^j(n)$, $\lambda_1^j(n)$ (the last three expressions are constant in n). We remark that, in the definition of $\left\| \sum_{i=1}^l e_i \right\|_1$, the admissible family achieving the maximum value, equal to $l/L(l) = \mathfrak{Q}(l)$, is $E_i = \{i\}$ ($1 \leq i \leq L$); therefore, $\|Z(l)\|_1 = 1 = \|x^i\|_1$ for $l, i \geq 1$ (by (1) and (4)), proving (8) for $k = 1$.

Using the family $\{I^i\}_{i=1}^M$ in the definition of $\|\cdot\|_2$, we have $\|E_i Y(n)\|_1 = \|x^i\|_1 = 1$ (by translation invariance of $\|\cdot\|_1$), hence the lower bound

$$\|Y(n)\|_2 \geq \frac{1}{L(M)} \sum_1^M 1 = \frac{M}{L(M)} = \mathfrak{Q}(M) \geq 3n,$$

since $M = \mathfrak{Q}^*(3n)$. This proves (10).

To find an upper bound for $\|Y(n)\|_1$, note first that the coefficients of the basis elements e_j in $Y(n)$ decrease with j (since the sequence $1/\mathfrak{Q}(\lambda^i)$ decreases with i). By the definitions of $\|\cdot\|_0$ and $\|\cdot\|_1$, a moment's reflection shows that a family realizing the maximum that defines $\|Y(n)\|_1$ must consist of, say, l singletons $E_i = \{i\}$ for some $l \leq \Lambda(n)$ and $1 \leq i \leq l$. Choose $m \leq M$ so that

$l \in (\lambda^{\leq m-1}, \lambda^{\leq m}]$, and let $l' = l - (\lambda^{\leq m-1}) \leq \lambda^m$. Then, we have

$$\begin{aligned} \|Y(n)\|_1 &= \frac{1}{L(l)} \left(\sum_{i=1}^{m-1} \sum_{j=1}^{\lambda^i} x^i[j] + \sum_{j=1}^{l'} x^m[j] \right) = \frac{1}{L(l)} \left(\sum_{i=1}^{m-1} \frac{\lambda^i}{\mathfrak{Q}(\lambda^i)} + \frac{l'}{\mathfrak{Q}(\lambda^m)} \right) \\ &= \sum_{i=1}^{m-1} \frac{L(\lambda^i)}{L(l)} + \frac{l'}{L(l)\mathfrak{Q}(\lambda^m)} \leq \sum_{i=1}^{m-1} \frac{L(\lambda^i)}{L(\lambda^{m-1})} + \frac{\mathfrak{Q}(l')}{\mathfrak{Q}(\lambda^m)} \quad (\text{since } \lambda^i, l' \leq l) \quad (3.1) \\ &\leq \sum_{i=1}^{m-1} \frac{1}{2^{m-i-1}} + 1 \leq 2 + 1 = 3 \quad (\text{since } l' \leq \lambda^m \text{ and } L(\lambda^{i+1}) \geq 2L(\lambda^i)). \end{aligned}$$

This proves (9) and completes the proof of the base case $k = 1$ of the induction.

3.2.4. The inductive step. Now we carry out the inductive step of the proof of (8), (9) and (10). Assume they hold for some $k \geq 1$. Denote $\lambda_{k+1}^i(n)$, $v_{k+1}^i(n)$, $x_{k+1}^i(n)$, $X_{k+1}(n)$, $Y_{k+1}(n)$ and $I_{k+1}^i(n)$ by x_i , X , Y , I_i , λ_i and v_i . First, observe that $\|X_k(\cdot)\|_{k+1} = 1$ follows from the inductive hypothesis (2); therefore, $\|x_i\|_{k+1} = 1$ follows from (5), proving (8) for $k + 1$.

The intervals I_i ($1 \leq i \leq M$) satisfy $\|I_i Y\|_{k+2} = \|x_i\|_{k+2} = 1$. Using these intervals in the definition of $\|\cdot\|_{k+2}$ we obtain

$$\|Y_{k+1}(n)\|_{k+2} \geq \frac{1}{L(M)} \sum_{i=1}^M \|x_{k+1}^i(n)\|_{k+1} = \frac{M}{L(M)} = \mathfrak{Q}(M) \geq 3n.$$

This proves (10) for $k + 1$.

To prove (9) for $k + 1$, we start as in the proof of the base case. Since the coefficients of Y are decreasing, a moment's reflection shows that, an admissible family achieving the maximum that defines $\|Y_{k+1}(n)\|_{k+1}$ may be taken to consist of intervals $E_1 < E_2 < \dots < E_m$. By the monotonicity of $\|\cdot\|_k$, the maximizing E_j 's may be taken to be the back-to-back intervals such that $\bigcup_{i=1}^m E_i = [1, \Lambda] = \bigcup_{j=1}^M I_j$.

A pair (j, i) with $1 \leq j \leq m$ and $1 \leq i \leq M$ will be called *relevant* if $E_j \cap I_i$ is nonempty.

We split the intervals $[1, m]$ into two disjoint subclasses:

(\subseteq) This class consists of those j such that $E_j \subseteq I_i$ for some i .

($\not\subseteq$) This is the complementary class consisting of those relevant j such that for no i is E_j a subset of I_i .

We will use the symbols " \subseteq ", " $\not\subseteq$ " as nomenclature for the corresponding class. Abusing the nomenclature, we will say that $i \in [1, M]$ is of class \subseteq if (j, i) is of class \subseteq for some j . With these notations, we have

$$\|Y\|_{k+1} = \sum_{\subseteq} + \sum_{\not\subseteq}, \quad (3.2)$$

where

$$\sum_{\subseteq} := \sum_j \frac{\|E_j Y\|_k}{L(m)}, \quad \sum_{\not\subseteq} := \sum_j \frac{\|E_j Y\|_k}{L(m)}.$$

We will find an upper bound for each of the two sums above.

Case \subseteq : Consider any fixed $i \leq M$ of class \subseteq . Let m_i be the number of indexes j of class \subseteq for i ; they form an interval, say $[r_i, r_i + m_i - 1]$. Since such E_j are disjoint nonempty subsets of I_i ,

and $\#I_j = \lambda_j$, we have $m_i \leq \min\{M, \lambda_i\}$. Now, we have

$$\sum_{\subseteq}^{\subseteq} = \sum_j^{\subseteq} \frac{\|E_j Y\|_k}{L(m)} = \sum_i^{\subseteq} \sum_{j=r_i}^{r_i+m_i-1} \frac{\|E_j Y\|_k}{L(m)}. \quad (3.3)$$

as seen by using the family $\{E_j\}_{j=s_i}^{s_i+m_i-1}$ in the recursive definition of $\|I_1 Y\|_{k+1}$, which is admissible precisely because such (i, j) are of type \subseteq .

If there exists $i \in [1, M]$ of class \subseteq such that $m_i > v_i$, let p denote the largest such j ; otherwise, let $p = 0$. Thus, every $i > p$ of class \subseteq satisfies $m_j \leq v_j$. Continuing from (3.3), we write

$$\sum_{\subseteq}^{\subseteq} = \sum_{\leq p}^{\subseteq} + \sum_{> p}^{\subseteq}, \quad (3.4)$$

where $\sum_{\leq p}^{\subseteq}$, $\sum_{> p}^{\subseteq}$ are the sums over (class- \subseteq) indices $i \leq p$, $i > p$, respectively, on the right-hand side of (3.3).

If $p > 0$, we have

$$\begin{aligned} \sum_{\leq p}^{\subseteq} &:= \sum_{i \leq p}^{\subseteq} \sum_{j=r_i}^{r_i+m_i-1} \frac{\|E_j Y\|_k}{L(m)} \leq \sum_{i \leq p}^{\subseteq} \frac{L(m_i) \|I_i Y\|_{k+1}}{L(m)} \\ &\quad (\text{by definition of } \|\cdot\|_{k+1}, \text{ since } \{E_j\}_{j=r_i}^{r_i+m_i-1} \text{ is an admissible family of subsets of } I_i) \\ &= \sum_{i \leq p}^{\subseteq} \frac{L(m_i) \|x_i\|_{k+1}}{L(m)} = \sum_{i \leq p}^{\subseteq} \frac{L(m_i)}{L(m)} \quad (\text{by property (8)—already proved for } k+1) \\ &\leq 1 + \sum_{i=1}^{p-1} \frac{L(\lambda_i)}{L(v_p)} \quad (\text{since } m_i \leq \lambda_i \text{ and } m \geq m_p > v_p, \text{ by choice of } p) \\ &\leq 1 + \sum_{i=1}^{p-1} \frac{L(\lambda_i)}{L(v_{i+1})} = 1 + \sum_{i=1}^{p-1} \frac{L(\lambda_i)}{L(v_{i+1})} = 1 + \sum_{i=1}^{p-1} \frac{1}{2^i} \\ &\quad (\text{since } v_i < v_p \text{ for } i < p, \text{ and } L(v_{i+1}) = 2^i L(\lambda_i) \text{ by construction}). \end{aligned} \quad (3.5)$$

We have $\sum_{\leq p}^{\subseteq} = 0$ if $p = 0$, i.e., if there are no class- \subseteq indexes i such that $m_i > v_i$, so the upper bound (equal to 1) on the right-hand side of inequality (3.5) remains valid in this case as well.

We now estimate $\sum_{> p}^{\subseteq}$. Just as in the case of $\sum_{\leq p}^{\subseteq}$ above, have $\sum_{> p}^{\subseteq} = 0$ if there is no index $i > p$ (perhaps no index i at all) of class \subseteq . Letting $n_i = 2^i v_i$, we have

$$\|x_i\|_k = \|X_k(n_i)\|_k = \frac{\|Y_k(n_i)\|_k}{\|Y_k(n_i)\|_{k+1}} \leq \frac{3}{3n_i} = \frac{1}{2^i v_i}. \quad (3.6)$$

We get,

$$\begin{aligned} \sum_{>p}^{\subseteq} &:= \sum_{i>p}^{\subseteq} \sum_{j=r_i}^{r_i+m_i-1} \frac{\|E_j Y\|_k}{L(m)} = \sum_{i>p}^{\subseteq} \sum_{j=r_i}^{r_i+m_i-1} \frac{\|I_i Y\|_k}{L(m)} = \sum_{i>p}^{\subseteq} \frac{m_i \|x_i\|_k}{L(m)} \\ &\quad (\text{by monotonicity of } \|\cdot\|_k, \text{ since } E_j \subseteq I_i; \text{ furthermore, } I_i Y \text{ is a shift of } x_i) \\ &\leq \sum_{i>p}^{\subseteq} \frac{v_i \|x_i\|_k}{L(m)} \leq \sum_{i>p}^{\subseteq} \frac{2^{-i}}{L(m)} \leq \sum_{i=p+1}^{\infty} \frac{1}{2^i} \quad (\text{by (3.6), since } m_i \leq v_i \text{ for } i > p \text{ of class } \subseteq). \end{aligned} \quad (3.7)$$

Combining estimates (3.5) and (3.7) we obtain

$$\sum_{\subseteq}^{\subseteq} \leq 2. \quad (3.8)$$

Case $\not\subseteq$: For j of class $\not\subseteq$, the relevant indexes i fill an interval $J_j = [s_j, s_j + n_j - 1]$ of length $n_j \geq 2$. For each $i \in [1, M]$, let μ_i be the number of j of class $\not\subseteq$ such that (j, i) is relevant. Clearly, $0 \leq \mu_i \leq 2$. Define $F_{ji} = E_j \cap I_i$. By the triangle inequality and monotonicity,

$$\begin{aligned} \sum_{\not\subseteq} &:= \sum_j^{\not\subseteq} \frac{\|E_j Y\|_k}{L(m)} \leq \sum_j^{\not\subseteq} \sum_{i=s_j}^{s_j+n_j-1} \frac{\|F_{ji} Y\|_k}{L(m)} \leq \sum_j^{\not\subseteq} \sum_{i=s_j}^{s_j+n_j-1} \frac{\|I_i Y\|_k}{L(m)} \\ &= \sum_i \mu_i \frac{\|I_i Y\|_k}{L(m)} = 2 \sum_i \frac{\|x_i\|_k}{L(m)} \leq \frac{2}{L(m)} \sum_{i=1}^M \frac{1}{2^i v_i} \leq \frac{2}{v_1} = 1. \end{aligned} \quad (3.9)$$

By (3.2), (3.8) and (3.9) we have proved (9) for $k + 1$, completing the inductive step and the proof of Proposition 17.

3.3. Non-Definability of the Schlumprecht Norm.

18. Theorem. *Lemma 5, Propositions 4 and 6, and Theorem 12 hold for the Schlumprecht norm $\|\cdot\|_{\mathcal{S}}$ and its approximants $\|\cdot\|_k$ in place of $\|\cdot\|_T$ and $\|\cdot\|_k$ therein.*

Proof. With the indicated one-for-one replacements, the proofs go through verbatim provided at the beginning of the proof of the revised Lemma 5 we take $y = Y_k(3)/3$ as per Proposition 17 (with $n = 3$), whose Schlumprecht approximants satisfy $\|y\|_k \leq 1$ and $\|y\|_{k+1} \geq 3$. \square

The *classical Schlumprecht structure* \mathcal{S} is the Nseq structure obtained from Schlumprecht space \mathcal{S} by interpreting $\|\cdot\|_k$ as the Schlumprecht approximants, and the master norm $\|\cdot\|$ as the Schlumprecht norm on \mathcal{S} . $\text{Th}_{\mathcal{S}}$ is the L_{Nseq} -theory of \mathcal{S} . A *Schlumprecht structure* is any model of $\text{Th}_{\mathcal{S}}$.

The following analogue of Theorem 14 holds. Since the analogue of Theorem 12 (for the Schlumprecht norm) holds, the proof is *mutatis mutandis* the same, and omitted.

19. Theorem (First-Order Non-Definability of the Schlumprecht Norm). *The Schlumprecht norm $\|\cdot\|_T^{\mathcal{M}}$ is not definable over L_{Nseq} -structures \mathcal{M} that satisfy either of the following properties:*

- \mathcal{M} is an elementary extension of the classical Schlumprecht space \mathcal{S} , or
- \mathcal{M} is a countably saturated model of $\text{Th}_{\mathcal{S}}$.

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